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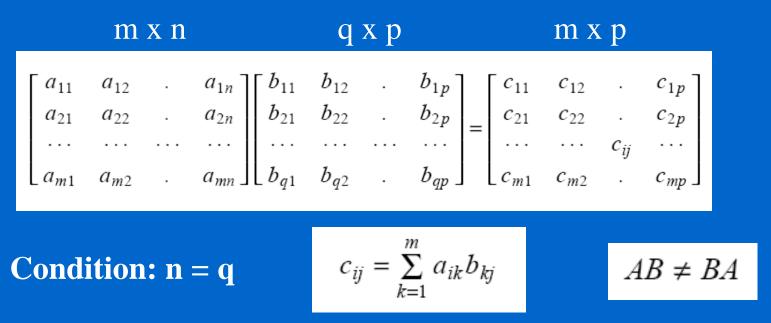
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Matrix Analysis

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Matrix Operations

- Matrix addition/subtraction
 - Matrices must be of same size.
- Matrix multiplication



Identity Matrix

$$AI = IA = A$$
, where $I = \begin{bmatrix} 1 & 0 & . & 0 \\ 0 & 1 & . & 0 \\ ... & ... & ... \\ 0 & 0 & . & 1 \end{bmatrix}$

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Matrix Transpose

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}, A^{T} = \begin{bmatrix} a_{11} & a_{21} & \dots & a_{m1} \\ a_{12} & a_{22} & \dots & a_{m2} \\ \dots & \dots & \dots & \dots \\ a_{1n} & a_{2n} & \dots & a_{mn} \end{bmatrix}$$

Property:
$$(AB)^T = B^T A^T$$

Symmetric Matrices

$$A=A^T (a_{ij}=a_{ji})$$

Example:

$$\begin{bmatrix} 4 & 5 & -3 \\ 5 & 7 & 2 \\ -3 & 2 & 10 \end{bmatrix}$$

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Determinants

$$\begin{aligned} 2 \ge 2 \\ A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}, \quad det(A) = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = a_{11}a_{22} - a_{21}a_{12} \end{aligned}$$

3 x 3

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{21} \begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} + a_{31} \begin{vmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{vmatrix}$$

n x n

$$det(A) = \sum_{j=1}^{m} (-1)^{j+k} a_{jk} det(A_{jk}), \text{ for any } k: 1 \le k \le m$$

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Determinants

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$$det(AB) = det(A)det(B)$$

$$det(A + B) \neq det(A) + det(B)$$

diagonal matrix:

If
$$A = \begin{bmatrix} a_{11} & 0 & . & 0 \\ 0 & a_{22} & . & 0 \\ . & . & . & . \\ . & . & . & . \\ 0 & 0 & . & a_{nn} \end{bmatrix}$$
, then $det(A) = \prod_{i=1}^{n} a_{ii}$

Matrix Inverse

lacksquare

- The inverse A^{-1} of a matrix A has the property: $AA^{-1}=A^{-1}A=I$
- A^{-1} exists only if $det(A) \neq 0$

Matrix Inverse (cont'd)

• Properties of the inverse:

$$det(A^{-1}) = \frac{1}{det(A)}$$
$$(AB)^{-1} = B^{-1}A^{-1}$$
$$(A^{T})^{-1} = (A^{-1})^{T}$$

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Pseudo-inverse

• The pseudo-inverse *A*⁺ of a matrix A (could be non-square, e.g., m x n) is given by:

$$A^+ = (A^T A)^{-1} A^T$$

• It can be shown that:

$$A^+A = I$$
 (provided that $(A^TA)^{-1}$ exists)

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Matrix trace

$$tr(A) = a_{11} + a_{22} + \dots + a_{nn}$$

properties:

 $tr(A^{T}) = tr(A)$ $tr(A \pm B) = tr(A) \pm tr(B)$ tr(AB) = tr(BA)(in general, $tr(AB) \neq tr(A)tr(B)$)

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Rank of matrix

• Equal to the dimension of the largest square submatrix of *A* that has a non-zero determinant.

Example:

$$\begin{bmatrix} 4 & 5 & 2 & 14 \\ 3 & 9 & 6 & 21 \\ 8 & 10 & 7 & 28 \\ 1 & 2 & 9 & 5 \end{bmatrix}$$

$$det(A) = 0, \text{ but } det\begin{pmatrix} 4 & 5 & 2 \\ 3 & 9 & 6 \\ 8 & 10 & 7 \end{pmatrix} = 63 \neq 0$$

Rank of matrix (cont'd)

• <u>Alternative definition</u>: the maximum number of linearly independent columns (or rows) of *A*.

$$c_1v_1 + c_2v_2 + \dots + c_kv_k = 0$$
 $c_1 = c_2 = \dots = c_k = 0$

Example:

$$\begin{bmatrix}
4 \\
3 \\
8 \\
1
\end{bmatrix} + 2
\begin{bmatrix}
5 \\
9 \\
10 \\
2
\end{bmatrix} + 0
\begin{bmatrix}
2 \\
6 \\
7 \\
9
\end{bmatrix} - 1
\begin{bmatrix}
14 \\
21 \\
28 \\
5
\end{bmatrix} = 0$$

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Therefore, rank is not 4 !

Rank and singular matrices

If A is nxn, rank(A) = n iff A is nonsingular (i.e., invertible). If A is nxn, rank(A) = n iff $det(A) \neq 0$ (full rank). If A is nxn, rank(A) < n iff A is singular

Orthogonal matrices

• Notation:

$$A = \begin{bmatrix} a_{11} & a_{12} & . & a_{1n} \\ a_{21} & a_{22} & . & a_{2n} \\ ... & ... & ... \\ a_{m1} & a_{m2} & . & a_{mn} \end{bmatrix}, \qquad \begin{bmatrix} u_1^T = \begin{bmatrix} a_{11} & a_{12} & ... & a_{1n} \end{bmatrix} \\ u_2^T = \begin{bmatrix} a_{21} & a_{22} & ... & a_{2n} \end{bmatrix} \\ ... \\ u_m^T = \begin{bmatrix} a_{m1} & a_{m2} & ... & a_{mn} \end{bmatrix}, \qquad A = \begin{bmatrix} u_1^T \\ u_2^T \\ ... \\ u_m^T \end{bmatrix}$$

• A is orthogonal if:

 $u_{j}. u_{k} = 0, \text{ for every } j \neq k (u_{j} \text{ is perpendicular to } u_{k})$ **Example:** $\begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$

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Orthonormal matrices

• A is orthonormal if:

Property:

(1)
$$u_k \cdot u_k = 1$$
 or $||u_k|| = 1$, for every k

(2) $u_j \cdot u_k = 0$, for every $j \neq k$ (u_j is perpendicular to u_k)

• Note that if A is orthonormal, it easy to find its inverse:

$$AA^T = A^T A = I \quad (i.e., A^{-1} = A^T)$$

||Av|| = ||v|| (does not change the magnitude of *v*)

Eigenvalues and Eigenvectors

• The vector **v** is an eigenvector of matrix A and λ is an eigenvalue of A if:

$$Av = \lambda v$$
 (assume non-zero v)

• **Interpretation:** the linear transformation implied by *A* cannot change the direction of the eigenvectors v, only their magnitude.

Computing λ and v

• To find the eigenvalues λ of a matrix *A*, find the roots of the *characteristic polynomial*:

$$det(A-\lambda I)=0$$

Example:
$$A = \begin{bmatrix} 5 & -2 \\ 6 & -2 \end{bmatrix}$$
$$Av = \lambda v$$

Properties

- Eigenvalues and eigenvectors are only defined for square matrices (i.e., *m* = *n*)
- Eigenvectors are not unique (e.g., if *v* is an eigenvector, so is *kv*)

$$Av = \lambda v$$

• Suppose $\lambda_1, \lambda_2, ..., \lambda_n$ are the eigenvalues of *A*, then:

(1)
$$\sum_{i} \lambda_{i} = tr(A)$$

(2) $\prod_{i} \lambda_{i} = det(A)$

(3) if $\lambda = 0$ is an eigenvalue, then the matrix is not invertible

Matrix diagonalization

- Given A, find *P* such that *P*¹*AP* is diagonal (i.e., P diagonalizes A)
- Take $P = [v_1 \ v_2 \ \dots \ v_n]$, where $v_1, v_2, \dots v_n$ are the eigenvectors of A:

Matrix diagonalization (cont'd)

Example:
$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\lambda_{1} = 0, \ \lambda_{2} = 2, \ v_{1} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \ v_{2} = \begin{bmatrix} 1 \\ 1 \end{bmatrix},$$
$$P = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}, \ P^{-1} = \begin{bmatrix} 1/2 & -1/2 \\ 1/2 & 1/2 \end{bmatrix}$$
$$P^{-1}AP = \begin{bmatrix} 0 & 0 \\ 0 & 2 \end{bmatrix}$$

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Are all n x n matrices diagonalizable?

Only if P⁻¹ exists (i.e., A must have n linearly independent eigenvectors, that is, rank(A)=n)

If A has n distinct eigenvalues λ₁, λ₂, ..., λ_n, then the corresponding eigevectors v₁, v₂, ..., v_n form a basis:
(1) linearly independent
(2) span Rⁿ

Diagonalization \rightarrow Decomposition

• Let us assume that A is diagonalizable, then:

$$P^{-1}AP = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ \vdots & \vdots & \vdots \\ 0 & \ddots & \vdots \\ \vdots & \vdots & \vdots \\ 0 & 0 & \lambda_n \end{bmatrix}$$

$$A = P \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ \vdots & \vdots & \vdots \\ \vdots & \ddots & \vdots \\ 0 & 0 & \lambda_n \end{bmatrix} P^{-1}$$

Decomposition: symmetric matrices

- The eigenvalues of symmetric matrices are all real.
- The eigenvectors corresponding to <u>distinct</u> eigenvalues are orthogonal.

$$A = P \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ \vdots & \vdots & \vdots \\ 0 & 0 & \lambda_n \end{bmatrix} P^{-1} \qquad P^{-1} = P^{T} = \sum_{i=1}^n \lambda_i v_i v_i^T$$